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RELIABILITY EVALUATION OF NETWORKS WITH IMPERFECT AND REPAIRABLE LINKS AND NODES

NIEZAWODNOŚĆ SIECI Z USZKADZAJĄCYMI SIĘ I ODNAWIANYMI POŁĄCZENIAMI ORAZ WĘZŁAMI*

The paper presents the method for determining the reliability of a network whose elements (links and nodes) are imperfect (can fail) and repairable. The presented method uses the factoring algorithm, proposed π method and computer simulation. The factoring algorithm is used to obtain a formula for accurate computation of network reliability as a probability of connectedness among the specified set of nodes K ($R_{N(K)}$). The reliability calculated in this way relates to cases when only links can fail and are unrepairable. In order to calculate the reliability of a network with repairable links and nodes, we introduced quasi-failures of links which occur as a result of failures of adjacent nodes – the π method. The developed method allows accounting for the repair of all the network elements after failure, as well as choosing the set of nodes (N_f) which can fail independently. In addition, the probability distributions of failure time of freely specified sets of nodes and links can be different. A simulation computational model was developed for the method which allows for determining the reliability ($R_{N(K)}(t)$) of a network with repairable links and nodes. Examples of numerical calculations were performed according to the developed model and the results are presented.

Keywords: network reliability, factoring algorithm, imperfect nodes, imperfect links, repairable elements, π method, simulation.

W opracowaniu przedstawiono metodę wyznaczania niezawodności sieci, w których elementy (połączenia i węzły) mogą się uszkadzać i są odnawiane. Przedstawiona metoda wykorzystuje algorytm faktoryzacji, zaproponowaną metodę π oraz symulację komputerową. Na podstawie algorytmu faktoryzacji wyznaczany jest wzór do dokładnego obliczania niezawodności sieci jako prawdopodobieństwa połączenia między wybranym zbiorem K węzłów ($R_{N(K)}$). Obliczana w ten sposób niezawodność dotyczy przypadków gdy tylko połączenia mogą się uszkadzać i nie są odnawiane. W celu obliczania niezawodności sieci z odnawianymi połączeniami i węzłami wprowadzono quasi uszkodzenia połączeń, które występują na skutek uszkodzeń węzłów do nich przyległych – metoda π . Opracowana metoda pozwala uwzględnić odnawianie wszystkich elementów sieci po uszkodzeniu jak również możliwość wyboru zbioru węzłów (N_f), które mogą się niezależnie uszkadzać. Ponadto rozkłady prawdopodobieństwa czasu pracy do uszkodzenia dowolnie określonych zbiorów węzłów i połączeń mogą być różne. Do zaproponowanej metody opracowano symulacyjny model obliczeniowy, który umożliwi wyznaczenie niezawodności sieci ($R_{N(K)}(t)$) z odnawianymi połączeniami i węzłami. Zgodnie z opracowanym modelem wykonano przykładowe obliczenia numeryczne i przedstawiono ich wyniki.

Słowa kluczowe: niezawodność sieci, algorytm faktoryzacji, uszkadzające się połączenia, uszkadzające się węzły, naprawialne elementy, metoda π , symulacja.

1. Introduction

Attempts to solve the network reliability issue have been made for years. The problem is important due to growing requirements in terms of reliable operation of various networks whose reliability is considered already at the design stage [8, 23]. Computer, communication, gas, water supply, power and other networks are still expanding and becoming increasingly complex. Determination of the reliability of such networks is complicated and in many cases is a NP-hard problem [1, 2, 20]. The solutions suggested in the literature most often relate to a determination of the reliability of undirected networks due to their coherence and structure of links [22] or due to their effective distribution [6,28]. There are also attempts to account for both aspects in the reliability evaluation [18].

Three kinds of accurate computations exist for the network reliability: exact [13], approximate and boundary values [5,10]. Since Moskovitz [14] used it as an accurate method of network reliability determination due to its coherence, the factoring algorithm has very often been used, investigated and modified [17, 21]. The net-

work model in the factoring algorithm is an undirected graph, and the reliability measure is the probability of connectedness among the specified set of nodes – K -terminal network reliability [7, 27]. The reliability is determined by a reduction of the graph representing the network with the assumption that the network nodes are perfectly reliable [3, 4]. The reliability determination of networks with failing links and nodes was also considered and the proposed computation methods were presented in [11, 24, 25]. As network reduction is significantly time-consuming, there was a search for quicker and more effective methods [12]. The following can be used for these purposes: series-parallel, polygon-to-chain, delta-to-star, degree-1 and degree-2 reductions, and also other methods [9, 2 6]. The formula obtained as a result of reduction allows computing a specified measure of network reliability for the chosen time. Practical applications of the factoring algorithm mainly regard real gas and water supply networks [15, 18] as well as computer networks [23].

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However, the reliability computed in this manner does not take into account the repair of failing network elements. The elements of real networks such as pipelines, telecommunication lines etc. are always repaired after failure. For the network reliability determination model to better reflect the reality, the repair of elements should be taken into account.

This paper presents the method of network reliability determination as the probability of connectedness among the specified set of nodes (K -terminal network reliability) taking into account the repair of failing links and nodes. The failures and repairs of nodes were implemented according to the proposed π method. The proposed model of reliability computation uses the classic factoring algorithm, the π method and the simulation method suitably adapted to them. The reliability computation for networks with repairable elements comprises two stages. In stage I, which is based on classic factoring algorithm, the formula is obtained for accurate computation of reliability of a network without repair of the elements. In stage II, the formula and the π method are used in the simulation procedure wherein the network reliability is determined when the nodes are repaired after failure.

2. Notation and assumptions

- $G=(V,E)$ – undirected graph which represents an undirected network,
- $V=(v_1,v_2,\dots,v_n)$ – set of vertices in a graph representing nodes in a network,
- $E=(e_1,e_2,\dots,e_m)$ – set of edges in a graph representing links in a network,
- v_j – vertex in a graph and node in a network, $v_j \in V$,
- e_i – edge in a graph and link in a network, $e_i \in E$,
- n – number of nodes in a network, $n=|V|$,
- N_f – set of nodes which can fail, $n_f \subseteq V$,
- m – number of links in a network, $m=|E|$,
- K – specified set of vertices in a graph (nodes in a network) which should be connected in order to guarantee the network’s operating state,
- G_K – graph with specified set $K \subseteq V$,
- $x_i(t)$ – state of link e_i at time t expressed in a binary manner, $x_i \in \{0,1\}$,
- $se_i(t)$ – state of link e_i at time t expressed in a numerical manner, $se_i \in \{1,0,-1,-2\}$,
- $p_i = Pr(x_i=1)$ – probability that link e_i is in an operating state,
- $q_i = 1 - p_i = Pr(x_i=0)$ – probability that link e_i is in a failure state,
- $R_{N(K)} = R(G_K)$ – network reliability – probability of connectedness among the specified set K of nodes (K -terminal network reliability),
- AM – adjacency matrix of a network,
- $X(t) = (x_1(t), x_2(t), \dots, x_m(t))$ – set of all links’ states at time t ,
- $Se(t) = (se_1(t), se_2(t), \dots, se_m(t))$ – set of all links’ states at time t expressed in a numerical manner,
- $\Phi(t) = R_{N(K)}(X(t))$ – function determining in a binary manner the network state at time t , $\Phi(t) \in \{0,1\}$,
- T_h – simulation time horizon,
- t_e – time of event,
- t_{fj} – time when the j th failure of link e_i occurs,
- t_{rj} – time when the j th repair of link e_i ends,
- t_{sf} – time when in s th simulation a network’s failure state occurs,
- S_{max} – number of simulation repetitions,
- $s_f(t)$ – number of simulations which until time t ended with occurrence of the network’s failure state,
- $R_{N(K)}(t)$ – reliability of a network with links and nodes repairable after failure.

The following assumptions were made in order to determine the network reliability using the proposed method:

- i Model of network is an undirected stochastic graph.

- ii The measure of network reliability is the probability that all nodes from specified set K are connected – K -terminal network reliability.
- iii All links e_i in the network can fail statistically independently of each other with known probability $q_i=1-p_i$, and the distribution of failure time of each is known.
- iv To obtain the formula for computation of network reliability $R_{N(K)}$, it is assumed that the nodes are perfectly reliable: $p_{v_i}=1$, and the links are unrepairable.
- v When determining the reliability $R_{N(K)}(t)$ of a network with failing and repairable elements, all the links and nodes can fail statistically independently of each other with known probabilities, and the distribution of failure time of each is known.
- vi A failure of a node in the network causes a quasi-failure of all links adjacent to the failed node.
- vii Each network link e_i and node v_j can be in only one of two states: operating or failure.
- viii Repair of each element results in restoration of its original reliability.

3. Determination of reliability of a network with perfect nodes and unrepairable links

The goal of stage I of the analysis is to obtain the formula for computation of reliability of a network with perfect nodes and unrepairable links. The factoring algorithm was used for this purpose. The formula $R_{N(K)}$ is obtained by reduction of the graph representing the network [16, 27]. The reduction process is based on a well-known principle of contracting and deleting of links which is recursively applied for all edges e_i in graph G . Examples of reduction for specified sets K are shown in Figure 1 (a: $|K|=|V|$; b: $|K|=2: \{v_1, v_2\}$).

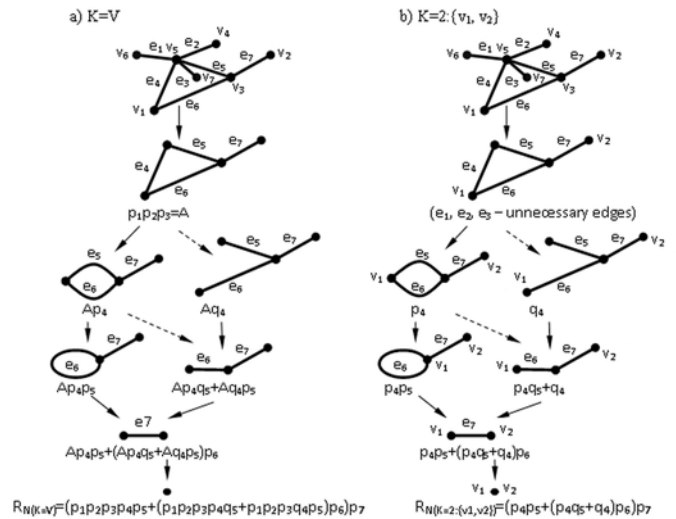


Fig. 1. Examples of reduction according to the factoring algorithm

4. Reliability of a network with imperfect and repairable links and nodes – π method

In stage II of the analysis we present the π method which takes into account the failures and repairs of links and nodes in the network.

Because, according to assumption vii, each link e_i can be only in one of two states, it was assumed that this state will be expressed in a

binary manner and denoted $x_i(t)$. As a result of failures and repairs, the values $x_i(t)$ can change in time as follows:

$$x_i(t) = \begin{cases} 1 - \text{link } e_i \text{ is in an operating state at time } t \\ 0 - \text{link } e_i \text{ is in a failure state at time } t \end{cases} \quad (1)$$

and the set of states of all links in the network at any time t is written as:

$$X(t) = (x_1(t), x_2(t), \dots, x_m(t)) \quad (2)$$

The following substitution for probability values p_i and q_i are made in formulas for network reliability ($R_{N(K)}$) obtained according to the factoring algorithm:

$$\begin{cases} p_i = x_i(t) \\ q_i = 1 - x_i(t) \end{cases} \quad (3)$$

Now, it can be noticed that after using formulas (1) – (3), the value of function $\Phi(t) = R_{N(K)}(X(t))$ in each case determines the network state in a binary manner due to the fact that the connectedness of nodes from set K : 1 – K nodes are connected, 0 – K nodes are not connected, which will be written as:

$$\Phi(t) = R_{N(K)}(X(t)) = \begin{cases} 1 - \text{operating state of network at time } t \\ 0 - \text{failure state of network at time } t \end{cases} \quad (4)$$

It is an easy method for determining the network state at any time t for each possible case $X(t)$ resulting from combination of states $x_i(t)$ of network links.

As each link e_i connects two nodes located on its ends (these nodes are adjacent to link e_i), the adjacency matrix (AM) for any network can be written in the following form:

$$AM = \begin{bmatrix} a_{i,j} & \dots & a_{i,n} \\ \vdots & \ddots & \vdots \\ a_{m,j} & \dots & a_{m,n} \end{bmatrix}; \quad \begin{matrix} i = 1, 2, \dots, m \\ j = 1, 2, \dots, n \end{matrix} \quad (5)$$

$$a_{i,j} = \begin{cases} 1 - \text{if node } v_j \text{ is one of two nodes adjacent to link } e_i \\ 0 - \text{if node } v_j \text{ isn't one of two nodes adjacent to link } e_i \end{cases} \quad (6)$$

Matrix AM will be used during calculation process to fastest finding the numbers of links which are in a failure state as a result of failure of nodes.

Analysing the structures of links in various networks, it is easy to notice that each link e_i which is adjacent to the failed node cannot be used to connect the specified set K of nodes. According to assumption v_i , such a state is called a quasi-failure of the link.

If nodes v_k and v_l are adjacent to link e_i , possible cases of failure and quasi-failures of link e_i are presented in Figure 2.

The cases presented in Figure 2 cause:

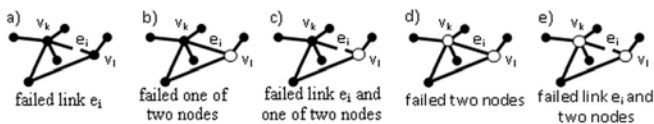


Fig. 2. Possible cases that caused a failure state and quasi-failures of link e_i

- 2a: failure of link e_i ,
- 2b: quasi-failure of link e_i ,
- 2c: failure and simultaneously quasi-failure of link e_i ,
- 2d: double quasi-failure of link e_i ,
- 2e: failure and simultaneously double quasi-failure of link e_i .

Each kind of link's failure is assumed in calculations as a failure state of that link.

The numerical value $se_i(t)$ which describes the link's state was introduced in order to allow for determining the number of failures at time t which cause the failure state of the link. If at time t the link e_i is in operating state, $se_i(t)=1$. Now, it was assumed that as a result of events, failures and repairs of link e_i and nodes v_k and v_l occurring at time t_e , values $se_i(t)$ of link e_i and other links adjacent to nodes v_k and v_l will change as follows:

- if link e_i at time t_e changes into failure state:

$$se_i(t > t_e) = se_i(t_e) - 1 \quad (7)$$

- if node v_k at time t_e changes into failure state:

$$\forall i (i \in (1, \dots, m) \wedge (AM(a_{i,j=k}) = 1) \Rightarrow se_i(t > t_e) = se_i(t_e) - 1) \quad (8)$$

- if node v_l at time t_e changes into failure state:

$$\forall i (i \in (1, \dots, m) \wedge (AM(a_{i,j=l}) = 1) \Rightarrow se_i(t > t_e) = se_i(t_e) - 1) \quad (9)$$

- if link e_i at time t_e changes into operating state:

$$se_i(t > t_e) = se_i(t_e) + 1 \quad (10)$$

- if node v_k at time t_e changes into operating state:

$$\forall i (i \in (1, \dots, m) \wedge (AM(a_{i,j=k}) = 1) \Rightarrow se_i(t > t_e) = se_i(t_e) + 1) \quad (11)$$

- if node v_l at time t_e changes into operating state:

$$\forall i (i \in (1, \dots, m) \wedge (AM(a_{i,j=l}) = 1) \Rightarrow se_i(t > t_e) = se_i(t_e) + 1) \quad (12)$$

hence, from formulas (7) – (12) we obtain the set of possible values $se_i(t)$ for each link:

$$se_i(t) = \left\{ \begin{array}{l} 1 - \text{operating state of link } e_i \text{ and both nodes } v_k, v_l \\ 0 - \text{failure state of link } e_i \text{ or node } v_k \text{ or node } v_l \\ -1 - \text{failure state of link } e_i \text{ and one of two nodes } v_k, v_l \text{ or} \\ \quad \text{operating state of link } e_i \text{ and failure state of both nodes } v_k, v_l \\ -2 - \text{failure state of link } e_i \text{ and both nodes } v_k, v_l \end{array} \right\} \quad (13)$$

The set of values $se_i(t)$ for all links in the network will be written as:

$$Se(t) = (se_1(t), se_2(t), \dots, se_m(t)) \quad (14)$$

Because each type of link failure is assumed in calculations as its failure state, the state of link $x_i(t)$ can be expressed in a binary manner, rewriting the formula (1) in the following form:

$$x_i(t) = \begin{cases} 1 - \text{if } se_i(t) = 1; \text{ operating state of link } e_i \\ 0 - \text{if } se_i(t) < 1; \text{ failure state of link } e_i \end{cases} \quad (15)$$

This proposed method of accounting for failures and repairs of links and nodes in the network (7) – (15) is called the π method (3.14) because:

- the state of each link depends on 3 elements: the link and two nodes adjacent to this link,
- there is only 1 possibility when the link is in an operating state: the link and both nodes adjacent to this link are in an operating state,
- the state of each link is quantified by a maximum 4 values: $se_i(t) \in \{1, 0, -1, -2\}$.

In this way, using the π method we determine the state of link e_i taking into account failures of the link itself and failures of adjacent nodes.

Using formula (15) we now also obtain the set of states $X(t)$, and from formula (4) we can calculate function $\Phi(t)$. Hence, it is possible to determine the state of the whole network due to connections of nodes from set K , at imperfect and repairable links and nodes.

5. Implementation of the π method – simulation model for estimation network reliability

The simulation method is implemented according to the diagram which for the network from Figure 1a is exemplary presented in Figure 3. Successive values of failure times and repair times are sampled independently for each link e_i and node v_j (we used the method of inverse cumulative distribution function) [19]. These values are summed, thus making successive values of times t_{fij} and t_{rjij} . The process continues until the simulation time horizon (T_h) is reached, or until the network is in a failure state ($\Phi(t)=0$). The nodes failures are accounted for by means of quasi-failures of links according to the π method.

The method of results analysis by using: $R_{N(K)}$ formula, matrix AM and π method is presented in Table 1.

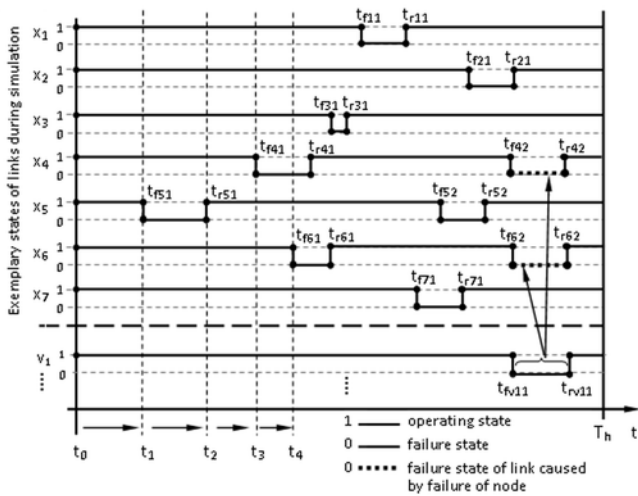


Fig. 3. Exemplary states of $x_i(t)$ of network links from Fig. 1a) during simulation

The presented method of sampling the time of events (failure and repair completion of the links and nodes) and of their analysis is applied in each simulation, which is repeated a specified number of times (s_{max}). The obtained values of times t_{sf} from all the simulations are then used to compute the reliability of a network with repairable links and nodes according to the formula:

$$R_{N(K)}(t) = 1 - \frac{s_f(t)}{s_{max}} \quad (16)$$

Table 1. Method of result analysis during simulation for link states from Figure 3

No.	t	X(t)	$R_{N(K=V)}$	$\Phi(t) = R_{N(K=V)}(X(t))$
1	t_0	$X(t_0) = (1,1,1,1,1,1,1)$	$(p_1 p_2 p_3 p_4 p_5 + [p_1 p_2 p_3 p_4 q_5 + p_1 p_2 p_3 q_4 p_5] p_6) p_7$ after applying (3): $(x_1(t)x_2(t)x_3(t)x_4(t)x_5(t) + [x_1(t)x_2(t)x_3(t)x_4(t)(1-x_5(t)) + x_1(t)x_2(t)x_3(t)(1-x_4(t))x_5(t)]x_6(t))x_7(t)$	1 – operating state
2	t_1	$X(t_1) = (1,1,1,1,0,1,1)$		1 – operating state
3	t_2	$X(t_2) = (1,1,1,1,1,1,1)$		1 – operating state
4	t_3	$X(t_3) = (1,1,1,0,1,1,1)$		1 – operating state
5	t_4	$X(t_4) = (1,1,1,0,1,0,1)$		0 – failure state of network: $t_4 = t_{sf}$

The simulation procedure was written as a computer program using the Matlab package. The program makes it possible to compute various measures of network reliability for the following cases:

- perfectly reliable nodes ($N_f = \emptyset$),
- failures and repairs of all network nodes ($N_f = V$),
- failures and repairs of a chosen set of nodes ($|N_f| < |V|$).

In addition, any subsets of failing links and nodes can have different probability distributions of failure time and different values of repair rate.

6. Example and results of application of the method

The developed method was applied to compute the reliability of network presented in Figure 4. The model of this network in the form of an undirected graph consists of 36 links and 34 nodes.

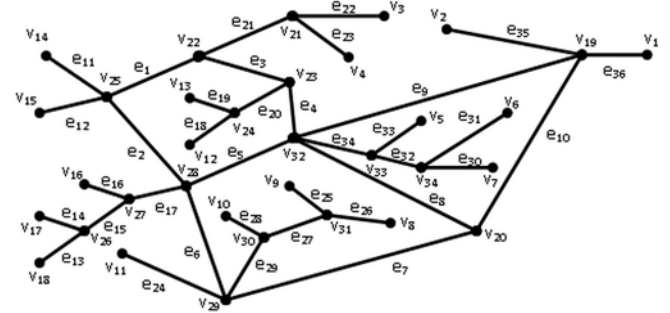


Fig. 4. Structure of the analysed network

Reductions were made for the analysed network according to the method presented in stage I, and the formulas were obtained to compute three different reliability measures: $R_{N(K=V)}$, $R_{N(K=2: \{v1, v14\})}$, $R_{N(K=18: \{v1 - v18\})}$. Formulas are extensive and are not presented.

Obtained formulas were used in the simulation computations. The probability distributions of failure time and of repair of nodes and links, along with the parameters used in simulations, are presented in Table 2. In all cases, the exponential distribution of repair probability and $\mu=10$ [1/t.u.] (t.u. – time unit) was assumed for nodes $v_j \in N_f$ and links e_i . The results of the computations for all cases from Table 3 are presented in Figures 5 and 6.

Table 2. Probability distributions and parameters used in the simulations

Network reliability measure	Set of nodes which can fail N_f	Probability distribution of failure time for nodes $v_j \in N_f$	Probability distribution of failure time for links $e_i \in E$
I: $R_{N(K=18);\{v1-v18\}}$	1) $N_f = \emptyset$: all nodes perfectly reliable	-	Exponential: $\lambda=3 \cdot 10^{-4}$ [1/t.u.]
II: $R_{N(K=18);\{v1-v18\}}$	1) $N_f = \emptyset$	-	Normal: $m=80$ [t.u.]; $\sigma=25$ [t.u.]
	2) $N_f = 16: \{v_{19}, \dots, v_{34}\}$	Weibull: $\alpha=1.9; \beta=150$ [t.u.]	
III: $R_{N(K=V)}$	3) $N_f = 16: \{v_{19}, \dots, v_{34}\}$	Weibull: $\alpha=1.9; \beta=100$ [t.u.]	Weibull: $\alpha=1.9; \beta=150$ [t.u.]
	1) $N_f = \emptyset$	-	
	2) $N_f = 16: \{v_{19}, \dots, v_{34}\}$	Weibull: $\alpha=1.9; \beta=150$ [t.u.]	
	4) $N_f = V: \{v_1, \dots, v_{34}\}$	Weibull: $\alpha=1.9; \beta=100$ [t.u.]	
IV: $R_{N(K=2);\{v1, v14\}}$	1) $N_f = \emptyset$	-	Normal: $m=80$ [t.u.]; $\sigma=25$ [t.u.]
	2) $N_f = 8: \{v_{19}, v_{20}, v_{22}, v_{23}, v_{25}, v_{28}, v_{29}, v_{32}\}$	Weibull: $\alpha=1.9; \beta=150$ [t.u.]	
	3) $N_f = \emptyset$	-	Weibull: $\alpha=1.9; \beta=150$ [t.u.]
	4) $N_f = 8: \{v_{19}, v_{20}, v_{22}, v_{23}, v_{25}, v_{28}, v_{29}, v_{32}\}$	Weibull: $\alpha=1.9; \beta=150$ [t.u.]	
	5) $N_f = 8: \{v_{19}, v_{20}, v_{22}, v_{23}, v_{25}, v_{28}, v_{29}, v_{32}\}$	Weibull: $\alpha=1.9; \beta=100$ [t.u.]	
			links e_{11}, e_{36} - Weibull: $\alpha=1.9; \beta=100$ [t.u.], other links - Normal: $m=80$ [t.u.]; $\sigma=25$ [t.u.]

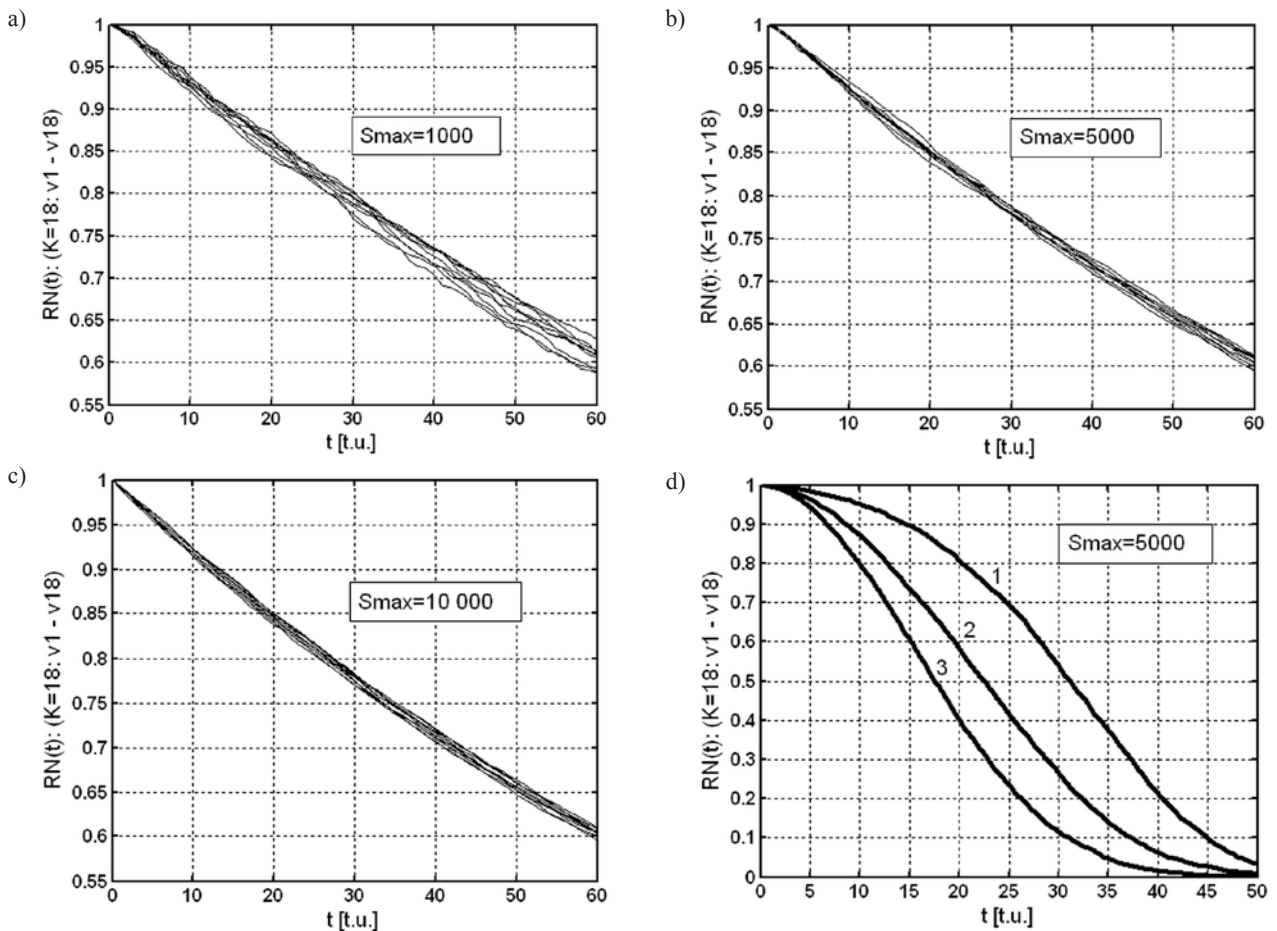


Fig. 5. Dispersion of results depending on the number of repetitions: a), b), c) – case I according to Table 2, and network reliability: d) – case II according to Table 2

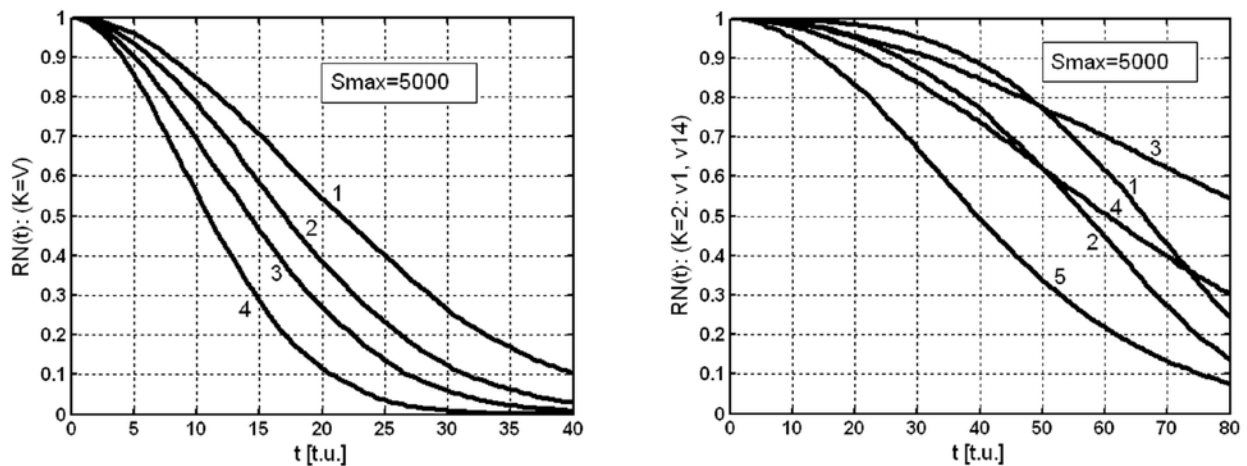


Fig. 6. Network reliability: a) – case III, b) – case IV according to Table 2

Figures 5a, 5b and 5c present the dispersion of results from 10 simulations depending on the number of repetitions (s_{max}) of a single simulation. One can notice that the increase of the number of repetitions s_{max} from 1000 to 5000 significantly improves the convergence of results, but increasing s_{max} to 10000 does not result in a significant improvement. The average computation time increased from 0.9 [s] to 2.6 [s], and for $s_{max}=10000$ to 4.9 [s]. The computations were performed on a standard PC with a 1.5 [GHz] processor and 2 [GB] RAM. Figure 5d presents the reliability of the analysed network $R_{N(K=18:\{v1-v18\})}(t)$ when the network nodes do not fail, and when the specified set of nodes N_f fails – case II in Table 2.

Figure 6a presents network reliability $R_{N(K=V)}(t)$ obtained for case III according to Table 2. Figure 6b presents another measure of network reliability $R_{N(K=2:\{v1,v14\})}(t)$, also obtained for various sets of failing nodes in the network and various probability distributions of failure time. In all cases, accounting for possible failures of a specified set of nodes or all nodes results in a reduced network reliability when compared to the situation with perfectly reliable nodes. For cases II, III and IV in Table 2, when the links and nodes failed, the calculation time at $s_{max}=5000$ was in the 5 – 20 [s] range.

7. Summary and critical discussion

The developed computation method allows determination of the various reliability measures for networks with repairable elements. This method can be used mainly for calculating structural reliability of real water and gas supply networks as well as logistics and different kind of telecommunications networks. Especially it can be useful for computer networks where links and nodes are completely different elements but both have strong influence on network reliability.

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The developed model can also be applied to compute the reliability of other complex technical systems with specified (known) reliability structures which contain repairable elements.

The proposed π method allows for accounting for the failures of both links and nodes in the network by the introduction of quasi-failures of links. After applying the π method, the formulas obtained according to the factoring algorithm which account only for the failure of links allow for an easy determination of the state of the whole network when both links and nodes fail. In the developed simulation model it is possible to use various probability distributions of failure time for any subsets of links and subsets of nodes which can fail (imperfect nodes). The failing elements can also have different values of repair rate.

The results indicate that using the models with perfectly reliable nodes ($N_f=\emptyset$) leads to overestimating the network reliability. Taking failures and repairs of nodes and links into account makes the model better reflect failures occurring in real networks. Hence, the presented model can be more useful in the analysis of practical cases, giving a more credible assessment of network reliability.

The inconvenience of the above method is the need to use the formulas obtained according to the factoring algorithm which, in the case of very complex network, are rather time-consuming to obtain. Further research can aim at searching for more effective network reduction methods and methods of obtaining formulas for sought network reliability measures $R_{N(K)}$, e.g. by development of computer algorithms or modification of the method and determination of the network reliability without the need to use them. Another interesting direction for future research can be a modification of the method for use in directed networks.

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